CS601: Software Development for Scientific Computing Autumn 2022

Week6: Motifs – Matrix Computations with Dense and Sparse Matrices

Last week..

- Three fundamental ways to multiply two matrices
	- Comprising of dot products, linear combination of the left matrix columns, outer product updates
		- Commonly occurring algorithmic patterns / kernels :

Dot product, AXPY and GAXPY, outer product, matrix-vector product, matrix-matrix product

- Linear algebra software (BLAS, LAPACK)
	- BLAS routines and categorization
- Algorithmic costs
	- Arithmetic cost
	- Data movement cost
- Computational intensity (examples: axpy, matvec, matmul)

Last week - Communication Cost

- loop $k=1$ to n: read $C(i,j)$ into fast memory and update in fast memory
- End of loop $k=1$ to n: write $C(i,j)$ back to slow memory
- Reading column j of B
- •, n^2 words read: each row of A read once for each i.
- Assume that row i of A stays in fast memory during $j=2, \ldots$ J=n
- Reading a row i of A

n² words read and n² words written (each entry of C read/written to memory once). = 2 n ²words read/written

total cost = $3 n² + n³$ (if the cache size is $n+n+1)$

- Suppose there is space in fast memory to hold only one column of B (in addition to one row of A and 1 element of C), then every column of B is read from slow memory to fast memory once in **inner two loops.**
- Each column of B read n times including **outer i loop =** n ³words read

Last week – Computational Intensity of Matmul (ijk)

- Words moved = $n^3+3n^2 = n^3+O(n^2)$
- Number of arithmetic operations $= 2n^3$ (from slide 35)
- computational intensity $q \approx 2n^3/n^3 = 2$. (computation to communication ratio)

Same as q for matrix-vector?

What if the fast memory has more space ? more than just two columns + one element space?

Can we do better?

Last week - Blocked Matrix Multiply

 $\left| \begin{array}{ccc} C1 & C2 & C4 \\ 1 & 1 & 1 \end{array} \right| = \left| \begin{array}{ccc} C1 & C2 & C3 & C4 \\ 1 & 1 & 1 \end{array} \right| + \left| \begin{array}{ccc} A & B1 & B2 & B3 \\ 1 & 1 & 1 \end{array} \right|$ • For $N=4$: $\begin{bmatrix} G \\ \end{bmatrix} = \begin{bmatrix} G \\ \end{bmatrix} + \begin{bmatrix} A \\ \end{bmatrix} + \begin{bmatrix} B \\ \end{bmatrix} = \begin{bmatrix} G \\ \end{bmatrix} + \sum_{k=1}^{n} k = 1$ $A(:,k)$ $Bj(k, :)$ for $j=1$ to N //Read entire Bj into fast memory //Read entire Cj into fast memory

for k=1 to n

//Read column k of A into fast memory

 $Cj = Cj + A(*,k) * Bj(k,*)$

Nikhil Hegde**//Write Cj back to slow memory** 5

source:<http://people.eecs.berkeley.edu/~demmel/cs267/lecture02.html>

Last week – Computational Intensity

For
$$
j=1
$$
 to N

\n//Read entire Bj into fast memory \rightarrow of B read once.

\n//Read entire Cj into fast memory for k=1 to n

\n//Read column k of A into fast memory

\nfor k=1 to n

\n//Read column k of A into fast memory column of A read N times

\n $C(*, j) = C(*, j) + A(*, k)*Bj(k, *) // outer-product$

\n//Write Cj back to slow memory

\n2n² words read:

\nNumber of arithmetic operations = $2n^3$ read/write each entry of C

\na. $a = 2n^3/(N+2)n^2 = 2n/N$ Good!

\n600

•
$$
q = 2n^3/(N+3)n^2 = 2n/N
$$
. Good!

Blocked Matrix Multiply - General

- $A, B, C \in \mathbb{R}^{n \times n}$
- We wish to update C block-by-block: $C_{ij} = C_{ij} + \sum_{k=1}^{p} A_{ik} B_{kj}$
	- Assume that blocks of A, B, and C fit in cache. C_{ij} is roughly n/q by n/r, A_{ij} is roughly n/q by n/p, B_{ij} is roughly n/p by n/r.
	- But how to choose block parameters p, q, r such that assumption holds for a cache of size M ?
		- i.e. given the constraint that $\frac{n}{q} \times \frac{n}{r}$ $\frac{n}{r}+\frac{n}{q}$ $\frac{n}{q} \times \frac{n}{p}$ $\frac{n}{p}+\frac{n}{p}$ $\frac{n}{p} \times \frac{n}{r}$ $\frac{n}{r} \leq M$

Blocked Matrix Multiply - General

• Maximize $\frac{2n^3}{\pi}$ qrp subject to $\frac{n}{2}$ \overline{q} × \boldsymbol{n} \boldsymbol{r} $+$ \boldsymbol{n} \overline{q} × \overline{n} \overline{p} $+$ \boldsymbol{n} \overline{p} × \boldsymbol{n} \boldsymbol{r} $\leq M$

$$
- q_{opt} = p_{opt} = r_{opt} \approx \sqrt{\frac{3n^2}{M}}
$$

- Each block should roughly be a square matrix and occupy one third of the cache size
- Can we design algorithms that are independent of cache size?

Recursive Matrix Multiply

- Cache-oblivious algorithm
	- No matter what the size of the cache is, the algorithm performs at a near-optimal level
- Divide-conquer approach

$$
\begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix} \times \begin{bmatrix} B_{11} & B_{12} \\ B_{21} & B_{22} \end{bmatrix} = \begin{bmatrix} A_{11}B_{11} + A_{12}B_{21} & A_{11}B_{12} + A_{12}B_{22} \\ A_{21}B_{11} + A_{22}B_{21} & A_{21}B_{12} + A_{22}B_{22} \end{bmatrix}
$$

- Apply the formula recursively to $A_{11}B_{11}$ etc. – Works neat when n is a power of 2.
- What layout format is preferred for this algorithm?
	- Row-major or Col-major? Neither.

Recursive Matrix Multiply

• Cache-oblivious Data structure

- Matrix entries are stored in the order shown
	- E.g. row-major would have 1-8 in the first row, followed by 9-16 in the second and so on.

Summary- matmul

• Unblocked Matrix Multiplication - Loop Orderings and **Properties**

Ref: Matrix Computations, 4th Ed., Golub and Van Loan

- Blocked matrix multiplication
	- Column blocking, row blocking, tiling
- Recursive matrix multiplication
	- Divide-conquer, Strassen's
- Many more?

Efficiency Considerations for a High-Performing Implementation

- Cache details (size)
- Data movement overhead
- Storage layout
- Parallel and 'special' functional Units (e.g. Vector units and fused multiply-add)

Parallel Functional Units

- IBM's RS/6000 and Fused Multiply Add (FMA)
	- Fuses multiply and an add into one functional unit (c=c+a*b)
	- The functional unit consists of 3 independent subunits : *Pipelining*
	- Example: Suppose the FMA unit takes 3 cycles to complete,

```
sum=0.0for (i=0;i< n;i++)sum=sum+a[i]*b[i]
```
how many cycles do you need to execute this code snippet?

```
sum=0.0
for (i=0;i<n;i+=4)
  sum1=sum1+a[i]*b[i]sum2=sum2+a[i+1]*b[i+1]sum3=sum3+a[i+2]*b[i+2]
  sum4 = sum4 + a[i+3] * b[i+3]how many cycles do you need to 
                          execute this code snippet?
```
Matrix Structure and Efficiency

- Sparse Matrices
	- E.g. banded matrices
	- Diagonal
	- Tridiagonal etc.
- Symmetric Matrices

Admit optimizations w.r.t.

- Storage
- **Computation**

Sparse Matrices - Motivation

• Matrix Multiplication with Upper Triangular Matrices $(C=C+AB)$

The result, A*B, is also upper triangular.

Nikhil Hegde 17 The non-zero elements appear to be like the result of *inner-product*

Sparse Matrices - Motivation

• C=C+AB when A, B, C are upper triangular for i=1 to N

for j=i to N

for k=i to j

 $C[i][j] = C[i][j] + A[i][k]*B[k][j]$

- Cost = $\sum_{i=1}^{N} \sum_{j=i}^{N} 2(j i + 1)$ flops (why 2?)
- Using $\Sigma_{i=1}^N i \approx \frac{n^2}{2}$ $\frac{n^2}{2}$ and $\Sigma_{i=1}^N i^2 \approx \frac{n^3}{3}$ 3
- $\Sigma_{i=1}^N \Sigma_{j=i}^N 2(j-i+1) \approx \frac{n^3}{3}$ 3 , 1/3rd the number of flops required for dense matrix-matrix multiplication

Sparse Matrices

• Have lots of zeros (a *large* fraction)

- Representation
	- Many formats available
	- Compressed Sparse Row (CSR)

Nikhil Hegde **19** double *val; int *ind; int *rowstart; Implementation: Three arrays:

Sparse Matrices - Example

• Using Arrays

double *val; //size= NNZ int *ind; //size=NNZ $int *rowsart; //size=M=Number of rows$

val:

ind:

Sparse Matrices: y=y+Ax

• Using arrays

for i=0 to numRows for j=rowstart[i] to rowstart[i+1]-1 $y[i] = y[i] + val[j]*x[ind[j]]$

- Does the above code reuse y, x, and val? (we want our code to reuse as much data elements as possible while they are in fast memory):
	- y? Yes. Read and written in close succession.
	- x? Possible. Depends on how data is scattered in val.
	- val? Less likely for a sparse matrix.

Sparse Matrices: y=y+Ax

• Optimization strategies:

for i=0 to numRows for j=rowstart[i] to rowstart[i+1]-1 $y[i] = y[i] + val[j]*x[ind[j]]$

- Unroll the j loop // we need to know the number of non-zeros per row
- Move y[i] outside the loop //Possible only if y is not aliased.
- Eliminate ind[i] and thereby the indirect access to elements of x. Indirect access is not good because we cannot predict the pattern of data access in x. //We need to know the column numbers
- Reuse elements of x //The elements of a should be e.g. located closely

Sparse Matrices

• Further reading:

Refer to Lecture 15 (Spring 2018) at <https://inst.eecs.berkeley.edu/~cs267/archives.html>

Banded Matrices

- Special case of sparse matrices, characterized by two numbers:
	- Lower bandwidth p, and upper bandwidth q

Banded Matrices - Representation

• Optimizing storage (specific to banded matrices)

Banded Matrices: $y = y + Ab$ and x

• A=Aband: optimizing computation and storage

```
for j=1 to n
  alpha1 = max(1, j-q)alpha2=min(n, j+p)
  beta1=max(1, q+2-j)for i=alpha1 to alpha2
     y[i]=y[i] + Aband(beta1+i-alpha1,j)*x[j]
```
• Cost? $2n(p+q+1)$ time! Much lesser than $2N^2$ time required for regular $y=y+Ax$ (assuming p and q are much smaller than n)