

CS601: Software Development for Scientific Computing

Autumn 2021

Week15:
Matrix Algebra

Course Progress..

- Last week: Matrix Algebra
 - Three fundamental ways to multiply two matrices
 - Commonly occurring algorithmic patterns
 - BLAS routines and categorization, Computational intensity
 - Efficiency considerations
 - Cache, Storage Layout, Data movement, Parallel Functional Units, Blocked Matrix Multiplication, Recursive Matrix Multiplication
- This week: Matrix algebra contd.

Matrix Structure and Efficiency

- Sparse Matrices
 - Banded matrices
 - Tridiagonal
 - Diagonal
 - Triangular
 - etc.
 - Symmetric Matrices
- 

- Storage
- Computation

How can we exploit the matrix structure to optimize for storage and computation?

Sparse Matrices - Motivation

- Matrix Multiplication with Upper Triangular Matrices ($C = C + AB$)
 - The result, A^*B , is also upper triangular

$$\left[\begin{array}{ccc|ccc} a_{11} & a_{12} & a_{13} & b_{11} & b_{12} & b_{13} \\ 0 & a_{22} & a_{23} & 0 & b_{22} & b_{23} \\ 0 & 0 & a_{33} & 0 & 0 & b_{33} \end{array} \right]$$

$$\begin{bmatrix} a_{11}b_{11} & a_{11}b_{12} + a_{12}b_{21} & a_{11}b_{13} + a_{12}b_{23} + a_{13}b_{13} \\ 0 & a_{22}b_{22} & a_{22}b_{23} + a_{23}b_{33} \\ 0 & 0 & a_{33}b_{33} \end{bmatrix}$$

Sparse Matrices - Motivation

- $C = C + AB$ when A, B, C are upper triangular
 - for $i=1$ to N
 - for $j=i$ to N
 - for $k=i$ to j
$$C[i][j] = C[i][j] + A[i][k]*B[k][j]$$
 - Cost = $\sum_{i=1}^N \sum_{j=i}^N 2(j - i + 1)$ flops (why 2? refer last week's slides)
 - Using $\sum_{i=1}^N i \approx \frac{n^2}{2}$ and $\sum_{i=1}^N i^2 \approx \frac{n^3}{3}$
 - $\sum_{i=1}^N \sum_{j=i}^N 2(j - i + 1) \approx \frac{n^3}{3}$, 1/3rd the number of flops required for dense matrix-matrix multiplication

Sparse Matrices - Motivation

- Matrix Multiplication with Upper Triangular Matrices ($C = C + AB$)
 - Crude estimation of flop count = $1/3^{\text{rd}}$ normal MatMul flop count.

$$\left[\begin{array}{ccc|ccc} a_{11} & a_{12} & a_{13} & b_{11} & b_{12} & b_{13} \\ 0 & a_{22} & a_{23} & 0 & b_{22} & b_{23} \\ 0 & 0 & a_{33} & 0 & 0 & b_{33} \end{array} \right]$$

$$\begin{bmatrix} a_{11}b_{11} & a_{11}b_{12}+a_{12}b_{22} & a_{11}b_{13}+a_{12}b_{23}+a_{13}b_{13} \\ 0 & a_{22}b_{22} & a_{22}b_{23}+a_{23}b_{33} \\ 0 & 0 & a_{33}b_{33} \end{bmatrix}$$

Sparse Matrices

- Have lots of zeros (a *large* fraction)

x	x	0	0	x	0	0	0	x
0	x	0	0	x	0	x	0	0
0	x	x	x	0	x	0	0	x
x	0	0	x	0	0	x	0	0
0	x	0	x	x	0	0	0	x
0	x	x	0	0	0	x	x	x

- Representation
 - Many formats available
 - Compressed Sparse Row (CSR)
 - Two Vector of Vectors: `vector<vector<double>> val;`
 - Three arrays:
`double *val; //size= NNZ`
`int *ind; //size=NNZ`
`int *rowstart; //size=M=Number of rows`

Sparse Matrices - Example

- Using Arrays

A									
a_{11}	a_{12}	0	0	a_{15}	0	0	0	a_{19}	
0	a_{22}	0	0	a_{25}	0	a_{27}	0	0	
0	a_{32}	a_{33}	a_{34}	0	a_{36}	0	0	a_{39}	
a_{41}	0	0	a_{44}	0	0	a_{47}	0	0	
0	a_{52}	0	a_{54}	a_{55}	0	0	0	a_{59}	
0	a_{62}	a_{63}	0	0	0	a_{67}	a_{68}	a_{69}	

```
double *val; //size= NNZ  
int *ind; //size=NNZ  
int *rowstart; //size=M=Number of rows
```

val:

a_{11}	a_{12}	a_{15}	a_{19}	a_{22}	a_{25}	a_{27}	a_{32}	a_{33}	a_{34}	a_{36}	a_{39}	a_{41}	a_{44}	a_{47}	a_{52}	a_{54}	a_{55}	a_{59}	a_{62}	a_{63}	a_{67}	a_{68}	a_{69}
----------	----------	----------	----------	----------	----------	----------	----------	----------	----------	----------	----------	----------	----------	----------	----------	----------	----------	----------	----------	----------	----------	----------	----------

ind:

1	2	5	9	2	5	7	2	3	4	6	9	1	4	7	2	4	5	9	2	3	7	8	9
---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

rowstart:

0	4	7	12	15	19	
---	---	---	----	----	----	--

Sparse Matrices - Example

$$\mathbf{A} = \begin{pmatrix} 1.5 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 2.3 & 0 & 1.4 & 0 & 0 & 0 & 0 \\ 0 & 0 & 3.7 & 0 & 0 & 0 & 0 & 0 \\ 0 & -1.6 & 0 & 2.3 & 9.9 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 5.8 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 7.4 & 0 & 0 \\ 0 & 0 & 1.9 & 0 & 0 & 0 & 4.9 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 3.6 \end{pmatrix}$$

ind		
1		
2	4	
3		
2	4	5
5		
6		
7	3	
8		

val		
1.5		
2.3	1.4	
3.7		
-1.6	2.3	9.9
5.8		
7.4		
4.9	1.9	
3.6		

Using vectors:

```
vector<vector<double>> val;  
vector<vector<int>> ind;
```

We represent a sparse matrix as two vectors of vectors:
`vector<vector<double> >`
to hold the matrix elements,
`vector<vector<int> >`
to hold the column indices.

Compressed-sparse-row (CSR) representation.

Sparse Matrices: $y=y+Ax$

- Using arrays

```
for i=0 to numRows  
    for j=rowstart[i] to rowstart[i+1]-1  
        y[i] = y[i] + val[j]*x[ind[j]]
```

- Does the above code reuse y , x , and val ? (we want our code to reuse as much data elements as possible while they are in fast memory):
 - y ? Yes. Read and written in close succession.
 - x ? Possible. Depends on how data is scattered in val .
 - val ? Less likely for a sparse matrix.

Sparse Matrices: $y=y+Ax$

- Optimization strategies:

```
for i=0 to numRows
    for j=rowstart[i] to rowstart[i+1]-1
        y[i] = y[i] + val[j]*x[ind[j]]
```

- Unroll the j loop // we need to know the number of non-zeros per row
- Move y[i] outside the loop //Possible only if y is not aliased.
- Eliminate ind[i] and thereby the indirect access to elements of x.
Indirect access is not good because we cannot predict the pattern of data access in x. //We need to know the column numbers
- Reuse elements of x //The elements of val should be e.g. located closely

Sparse Matrices

- Further reading:

Refer to Lecture 15 (Spring 2018) at

<https://inst.eecs.berkeley.edu/~cs267/archives.html>

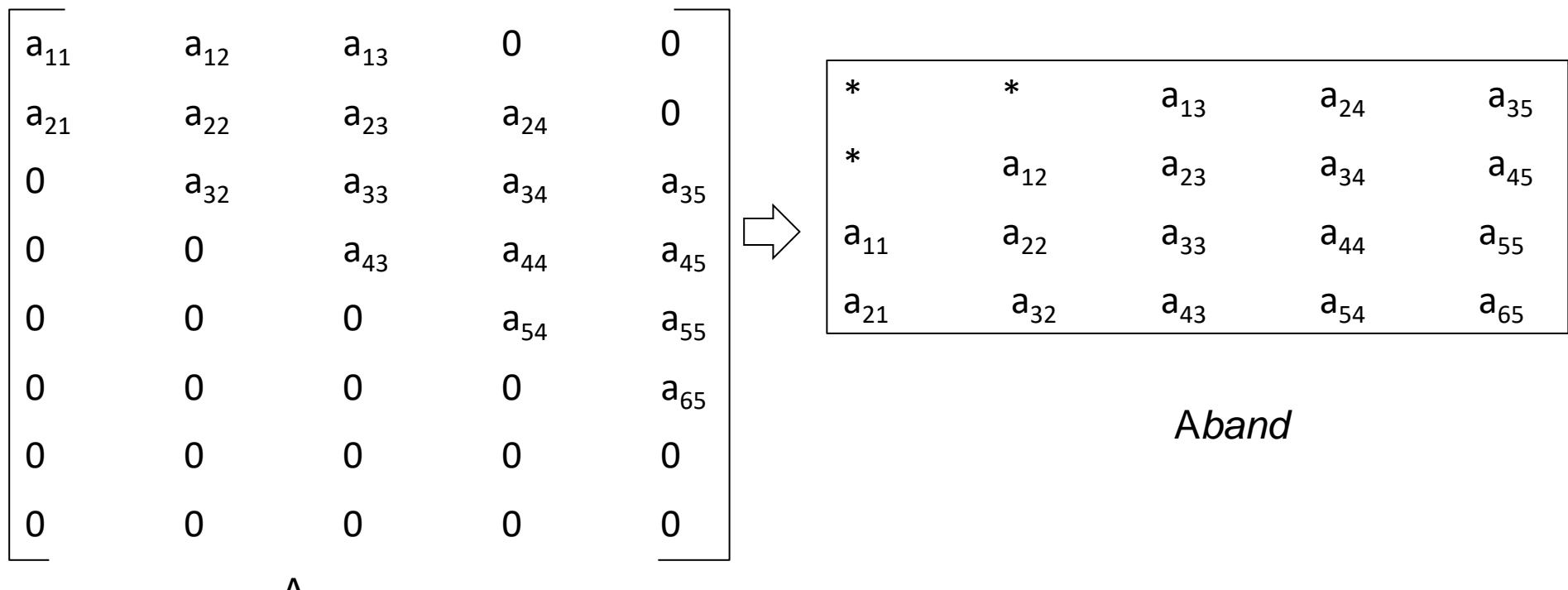
Banded Matrices

- Special case of sparse matrices, characterized by two numbers:
 - Lower bandwidth p , and upper bandwidth q
 - $a_{ij} = 0$ if $i > j+p$
 - $a_{ij} = 0$ if $j > i+q$
 - E.g. $p=1$, $q=2$
for a 8x5 matrix
(x represents non-zero element)

x	x	x	0	0
x	x	x	x	0
0	x	x	x	x
0	0	x	x	x
0	0	0	x	x
0	0	0	0	x
0	0	0	0	0
0	0	0	0	0

Banded Matrices - Representation

- Optimizing storage (specific to banded matrices)



$$A_{ij} = Aband(i-j+q+1, j)$$

E.g. $A_{44} = Aband_{34}$

Banded Matrices: $y = y + A_{\text{band}} x$

- $A=A_{\text{band}}$: optimizing computation and storage

```
for j=1 to n
    alpha1=max(1, j-q)
    alpha2=min(n, j+p)
    beta1=max(1, q+2-j)
    for i=alpha1 to alpha2
        y[i]=y[i] + Aband(beta1+i-alpha1, j)*x[j]
```

- Cost? $2(p+q+1)$ time! Much lesser than $2N^2$ time required for regular $y=y+Ax$ (assuming p and q are much smaller than n)

Banded Matrices

- Exercise: how much savings in memory do we get in A_{band} compared to the vector of vectors representation in slide 6? Assume that the matrix is 8x5.

Faster $y = Ax$: Discrete Fourier Transforms (DFT)

- Very widely used
 - Image compression (jpeg)
 - Signal processing
 - Solving Poisson's Equation
- Represent A with F, a *Fourier Matrix* that has the following (remarkable) properties:
 - F^{-1} is easy to compute and consists of real numbers
 - Multiplications by F and F^{-1} is fast.
- F has complex numbers in its entries.
 - Every entry is a power of a single number w such that $w^n=1$
 - Any entry of a Fourier matrix can be written using $f_{ij} = w^{ij}$ (row and col indices start from 0)

Example: Fourier Matrix

- 4x4: $F_4 = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & w & w^2 & w^3 \\ 1 & w^2 & w^4 & w^6 \\ 1 & w^3 & w^6 & w^9 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & w & w^2 & w^3 \\ 1 & w^2 & 1 & w^2 \\ 1 & w^3 & w^2 & w^1 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & i & i^2 & i^3 \\ 1 & i^2 & i^4 & i^6 \\ 1 & i^3 & i^6 & i^9 \end{bmatrix}, i = \sqrt{-1}$
 - Here, $w=i$ (also denoted as $w_4=i$). $w^4=1 \Rightarrow i$ is a root.
 - 8x8: $F_8 = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & w & w^2 & w^3 & w^4 & w^5 & w^6 & w^7 \\ 1 & w^2 & w^4 & w^6 & w^8 & w^{10} & w^{12} & w^{14} \\ 1 & w^3 & w^6 & w^9 & w^{12} & w^{15} & w^{18} & w^{21} \\ 1 & w^4 & w^8 & w^{12} & w^{16} & w^{20} & w^{24} & w^{28} \\ 1 & w^5 & w^{10} & w^{15} & w^{20} & w^{25} & w^{30} & w^{35} \\ 1 & w^6 & w^{12} & w^{18} & w^{24} & w^{30} & w^{36} & w^{42} \\ 1 & w^7 & w^{14} & w^{21} & w^{28} & w^{35} & w^{42} & w^{49} \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & w & w^2 & w^3 & w^4 & w^5 & w^6 & w^7 \\ 1 & w^2 & w^4 & w^6 & 1 & w^2 & w^4 & w^6 \\ 1 & w^3 & w^6 & w & w^4 & w^7 & w^2 & w^5 \\ 1 & w^4 & 1 & w^4 & 1 & w^4 & 1 & w^4 \\ 1 & w^5 & w^2 & w^7 & w^4 & w^1 & w^6 & w^3 \\ 1 & w^6 & w^4 & w^2 & 1 & w^6 & w^4 & w^2 \\ 1 & w^7 & w^6 & w^5 & w^4 & w^3 & w^2 & w^1 \end{bmatrix}$
- Here, $w = \frac{1+\sqrt{i}}{2}$
(sqrt of i)

Example: Fourier Matrix

- $$\left[\begin{array}{ccccccc} 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & w & w^2 & w^3 & w^4 & w^5 & w^6 & w^7 \\ 1 & w^2 & w^4 & w^6 & 1 & w^2 & w^4 & w^6 \\ 1 & w^3 & w^6 & w & w^4 & w^7 & w^2 & w^5 \\ 1 & w^4 & 1 & w^4 & 1 & w^4 & 1 & w^4 \\ 1 & w^5 & w^2 & w^7 & w^4 & w^1 & w^6 & w^3 \\ 1 & w^6 & w^4 & w^2 & 1 & w^6 & w^4 & w^2 \\ 1 & w^7 & w^6 & w^5 & w^4 & w^3 & w^2 & w^1 \end{array} \right] = \left[\begin{array}{cccc|cccc} 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & w^2 & w^4 & w^6 & w & w^3 & w^5 & w^7 \\ 1 & w^4 & 1 & w^4 & w^2 & w^6 & w^2 & w^6 \\ 1 & w^6 & w^4 & w^2 & w^3 & w & w^7 & w^5 \\ 1 & 1 & 1 & 1 & -1 & -1 & -1 & -1 \\ 1 & w^2 & w^4 & w^6 & -\omega & -\omega^3 & -\omega^5 & -\omega^7 \\ 1 & w^4 & 1 & w^4 & -\omega^2 & -\omega^6 & -\omega^2 & -\omega^6 \\ 1 & w^6 & w^4 & w^2 & -\omega^3 & -\omega & -\omega^7 & -\omega^5 \end{array} \right]$$

↑

(Writing columns 1,3,5,7 first and then columns 2,4,6,8
Also, using the fact that $w^4 = w^{2*}$ $w^2 = i^*i = -1$)

Example: Fourier Matrix

- $$\begin{bmatrix}
 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\
 1 & w & w^2 & w^3 & w^4 & w^5 & w^6 & w^7 \\
 1 & w^2 & w^4 & w^6 & 1 & w^2 & w^4 & w^6 \\
 1 & w^3 & w^6 & w & w^4 & w^7 & w^2 & w^5 \\
 1 & w^4 & 1 & w^4 & 1 & w^4 & 1 & w^4 \\
 1 & w^5 & w^2 & w^7 & w^4 & w^1 & w^6 & w^3 \\
 1 & w^6 & w^4 & w^2 & 1 & w^6 & w^4 & w^2 \\
 1 & w^7 & w^6 & w^5 & w^4 & w^3 & w^2 & w^1
 \end{bmatrix} =
 \left[\begin{array}{cccc|cccc}
 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\
 1 & w^2 & w^4 & w^6 & w & w^3 & w^5 & w^7 \\
 1 & w^4 & 1 & w^4 & w^2 & w^6 & w^2 & w^6 \\
 1 & w^6 & w^4 & w^2 & w^3 & w & w^7 & w^5 \\ \hline
 1 & 1 & 1 & 1 & -1 & -1 & -1 & -1 \\
 1 & w^2 & w^4 & w^6 & -\omega & -\omega^3 & -\omega^5 & -\omega^7 \\
 1 & w^4 & 1 & w^4 & -\omega^2 & -\omega^6 & -\omega^2 & -\omega^6 \\
 1 & w^6 & w^4 & w^2 & -\omega^3 & -\omega & -\omega^7 & -\omega^5
 \end{array} \right]$$

↑

(Partitioning into 4 matrix blocks of size 4x4.)

Example: Fourier Matrix

- $$\begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & w & w^2 & w^3 & w^4 & w^5 & w^6 & w^7 \\ 1 & w^2 & w^4 & w^6 & 1 & w^2 & w^4 & w^6 \\ 1 & w^3 & w^6 & w & w^4 & w^7 & w^2 & w^5 \\ 1 & w^4 & 1 & w^4 & 1 & w^4 & 1 & w^4 \\ 1 & w^5 & w^2 & w^7 & w^4 & w^1 & w^6 & w^3 \\ 1 & w^6 & w^4 & w^2 & 1 & w^6 & w^4 & w^2 \\ 1 & w^7 & w^6 & w^5 & w^4 & w^3 & w^2 & w^1 \end{bmatrix} = \begin{array}{c|c} \mathcal{F}_4 & \Omega_4 \mathcal{F}_4 \\ \hline \mathcal{F}_4 & -\Omega_4 \mathcal{F}_4 \end{array}$$

↑
(because $w^2 = w_4$)

$$\Omega_4 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & w & 0 & 0 \\ 0 & 0 & w^2 & 0 \\ 0 & 0 & 0 & w^3 \end{bmatrix} \quad (\text{note: } w = w_8 = \frac{1+\sqrt{i}}{2})$$
- $$\text{So, } F_8 = \begin{bmatrix} \mathcal{F}_4 & \Omega_4 \mathcal{F}_4 \\ \mathcal{F}_4 & -\Omega_4 \mathcal{F}_4 \end{bmatrix}$$

FFT

- We can obtain 8 point DFT from 4 point DFT.
- How do we obtain the result of F_8x , i.e. y , from F_4 and x ?
- $y[1] \text{ to } y[4] = y^{\text{top}} + d * y^{\text{bottom}}$
 - $d=[1, w, w^2, w^3]$ (note: $w= w_8 = \frac{1+\sqrt{i}}{2}$)
 - $y^{\text{top}} = F_4 x_{\text{odd}}$ ($x_{\text{odd}} = \text{elements at odd numbered indices of vector } x$)
 - $y^{\text{bottom}} = F_4 x_{\text{even}}$ ($x_{\text{even}} = \text{elements at even numbered indices of vector } x$)

Divide-and-Conquer FFT (D&C FFT)

$\text{FFT}(v, \omega, m)$... assume m is a power of 2

if $m = 1$ return $v[0]$

else

$v_{\text{even}} = \text{FFT}(v[0:2:m-2], \omega^2, m/2)$

$v_{\text{odd}} = \text{FFT}(v[1:2:m-1], \omega^2, m/2)$ precomputed

$\omega\text{-vec} = [\omega^0, \omega^1, \dots \omega^{(m/2-1)}]$

return $[v_{\text{even}} + (\omega\text{-vec} \cdot^* v_{\text{odd}}),$

$v_{\text{even}} - (\omega\text{-vec} \cdot^* v_{\text{odd}})]$

- Matlab notation: “ \cdot^* ” means component-wise multiply.

Cost: $T(m) = 2T(m/2)+O(m) = O(m \log m)$ operations.

FFT

- Refer to Lecture 20 (Spring 2018) at
<https://inst.eecs.berkeley.edu/~cs267/archives.html>
- Section 1.4, Matrix Computations, 4th Ed, Golub and Van Loan
- Section 3.5, Linear Algebra and Its Applications, 4th Ed, Gilbert Strang